# Compact course notes COMBINATORICS AND OPTIMIZATION 499

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 $Various \ topics$ 

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## 1 Foundational ideas

### 1.1 Lie Groups and their algebras

**Definition 1.1.1.** A group G is termed a Lie group iff its elements may be interpreted as coordinates of a finite-dimensional  $C^2$  manifold. Moreover, the group operations are  $C^2$  maps.

 $\mu: G \times G \to G \text{ given by } (x, y) \mapsto xy$  $\iota: G \to G \text{ given by } x \mapsto x^{-1}$ 

**Definition 1.1.2.** The tangent space of a group G at the identity element 1 or  $1_G$  is the topological tangent space to the manifold equivalent of  $\overline{G}$ , and is denoted by

$$\mathfrak{g} = T_1 G$$

**Definition 1.1.3.** Define several functions:

### 1.2 Tensors

Necessary to define: symmetrization, symmetric function, permutation

**Remark 1.2.1.** In this section we assume Einstein notation, and sum over all repeated indeces. If an index is not repeated in an expression, it takes on all values.

**Definition 1.2.2.** An rank n tensor in *m*-dimensional space is a mathematical object with  $m^n$  components. Tensors are generalizations in rank, and we note that:

- $\cdot$  scalars have rank 0
- $\cdot$  vectors have rank 1
- $\cdot$  matrices have rank 2

**Definition 1.2.3.** A tensor  $\alpha_{a,...c}^{d...f}$  with p lower and q upper indeces has <u>valence</u>  $\begin{bmatrix} p \\ q \end{bmatrix}$  and <u>rank</u> p + q.

**Definition 1.2.4.** A <u>covariant</u> tensor has lowered indeces, and a <u>contravariant</u> tensor has raised indeces. Lowered indeces themselves are sometimes termed covariant, and raised indeces are termed contravariant.

**Definition 1.2.5.** There are certain special tensors.

· the <u>Kronecker delta</u> symbol  $\delta_{ij} = \delta_i^j$  is a rank 2 tensor such that for any other rank 2 tensor  $\alpha_i^j$  we have

$$\delta^j_i \alpha^j_i = \sum_i \alpha^i_i = \sum_j \alpha^j_j$$

· the <u>Levi-Civita</u> symbol  $\epsilon_{ijk}$  is a rank 3 tensor such that for any other rank 3 tensor  $\alpha^{ijk}$  we have

$$\epsilon_{ijk}\alpha^{ijk} = \sum_{\text{even permutations} \atop \text{of } (ijk)} \alpha^{ijk} + \sum_{\text{odd permutations} \atop \text{of } (ijk)} \alpha^{ijk} + 0 \cdot \sum_{\substack{(ijk) \text{ has} \\ \text{repeated indeces}}} \alpha^{ijk}$$

Generalized in rank the above becomes the generalized Kronecker delta and the generalized Levi-Civita:

$$\delta_{i_1\dots i_k}^{j_1\dots j_k} \alpha_{i_1\dots i_k}^{j_1\dots j_k} = \sum_{\substack{i_1\dots i_k \\ i_1\dots i_k}} \alpha_{i_1\dots i_k}^{i_1\dots i_k} = \sum_{\substack{j_1\dots j_k \\ j_1\dots j_k}} \alpha_{j_1\dots j_k}^{j_1\dots j_k}$$
$$\epsilon_{i\dots k} \alpha^{i\dots k} = \sum_{\substack{\text{even permutations} \\ \text{of } (i\dots k)}} \alpha^{i\dots k} + \sum_{\substack{\text{odd permutations} \\ \text{of } (i\dots k)}} \alpha^{i\dots k} + 0 \cdot \sum_{\substack{(i\dots k) \\ \text{repeated indeces}}} \alpha^{i\dots k}$$

These two tensors are related, but it is not necessarily true that a single Levi-Civita tensor may be replaced by any sort of combination of Kronecker deltas, and vice versa.

$$\epsilon_{i_1...i_k} \epsilon^{j_1...j_k} = n! \delta_{[i_1}^{j_1} \delta_{i_2}^{j_2} \dots \delta_{i_k]}^{j_k}$$

#### 1.3Index bracket notation

Indeces may have round or square brackets around them, sometimes spanning several tensors, and never partly overlapping. Round brackets denote a symmetrizer over the included indeces. Square brackets denote an anti-symmetrizer or skew-symmetrizer over the included indeces.

As an example, take the following:

$$\alpha_a^{b[cd}\beta_e^{f]} = \alpha_a^{bcd}\beta_e^f - \alpha_a^{bcf}\beta_e^d - \alpha_a^{bdc}\beta_e^f + \alpha_a^{bfc}\beta_e^d + \alpha_a^{bdf}\beta_e^c - \alpha_a^{bfd}\beta_e^c$$

#### 1.4 Other base definitons

**Definition 1.4.1.** A function  $\Delta : \underbrace{\mathbb{F}^n \times \cdots \times \mathbb{F}^n}_{n \text{ times}} \to \mathbb{F}$  is termed <u>anti-symmetric</u> iff it is **1.** multilinear - linear in each variable

- 2. alternating takes negative value if any two inputs switched
- **3.** normalized  $\Delta(e_1,\ldots,e_n) = 1$

**Definition 1.4.2.** Define the *q*-binomial coefficient, or Gaussian coefficient to be the following:

$$\binom{m}{r}_q \stackrel{\circ}{=} \begin{cases} \frac{(1-q^m)(1-q^{m-1})\cdots(1-q^{m-r+1})}{(1-q)(1-q^2)\cdots(1-q^r)} & r \leq m\\ 0 & r > m \end{cases}$$

#### Algebras 2

**Definition 2.0.3.** A function  $F: A \to B$  between groups is termed a homomorphism if for all  $a, a' \in A$  $F(a *_A a') = F(a) *_B F(a')$ 

**Definition 2.0.4.** Let R be a ring. A ring A is termed an algebra over R if there exists a ring homomorphism  $F: R \to Z(A)$  for Z(A) the <u>center</u> of A, defined by

$$Z(A) \stackrel{\circ}{=} \{a \in A \mid ab = ba \text{ for all } b \in A\}$$

Let V be a vector space over a field  $\mathbb{F}$ . Then define a map  $p: V \otimes V \to V$  to be a product on V. We note that p is linear in each of its arguments.

Further, the pair  $\mathfrak{A} = (V, p)$  is termed an algebra of the vector space V endowed with p. This algebra is termed commutative iff the following diagram commutes.



An element  $1_{\mathfrak{A}}$  of an algebra  $\mathfrak{A}$  is termed a <u>unit</u> iff for all  $a \in \mathfrak{A}$  it satisfies

$$m(a \otimes 1_{\mathfrak{A}}) = m(1_{\mathfrak{A}} \otimes a) = a$$

We note that if an algebra has a unit, then it must be unique. With such a unit, the algebra is then termed an algebra with unit.

## 2.1 The symmetric algebra

**Definition 2.1.1.** Given a vector space V over a field  $\mathbb{F}$ , the tensor algebra over V is defined to be

$$T(V) = \bigoplus_{n \ge 0} V^{\otimes n} = \mathbb{F} \oplus V \oplus (V \otimes V) \oplus (V \otimes V \otimes V) \oplus \cdots$$

Every element of this algebra is strictly within some  $V^{\otimes n}$  for  $n \in \mathbb{N} \cup \{0\}$ .

**Definition 2.1.2.** The symmetric group, or permutation group of order n is the group with elements that are ordered permutations of the sequence  $\{1, 2, ..., n\}$ . It is denoted by  $S_n$  or  $\mathfrak{S}_n$ .

**Definition 2.1.3.** The symmetric algebra over a vector space V over a field  $\mathbb{F}$  is defined to be the space

$$S(V) \stackrel{\circ}{=} \bigoplus_{k \geqslant 0} S(V)^k = \bigoplus_{k \geqslant 0} \frac{T(V)^{\otimes k}}{\mathfrak{S}_n}$$

where  $T(V)^{\otimes k}$  is the set of elements in T(V) that may be expressed as k-dimensional tensors. The quotient of this space by the symmetric group ensures that the tensor product is commutative.